



Exploring the BBRv2 Congestion Control Algorithm for use on Data Transfer Nodes

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TCP Congestion Control 40 year History

- 1981 Base specification [RFC 793]
- 1986: TCP Reno (First appeared in BSD4.3)
- 1988 Van Jacobson's landmark TCP paper
- 1996: "Mathis Equation" paper defining relationship between loss and bandwidth
- 1997: TCP Slow Start, Congestion Avoidance, Fast Retransmit, and Fast Recovery (RFC2001)
- 1999: New Reno (RFC 2582)
- 2004: Cubic TCP released
- 2005: Fast TCP and Hamilton TCP (H-TCP) released
- 2006: Cubic becomes the default in Linux
- 2013: ESnet's TCP slide motivation for a Science DMZ (next slide)
- 2013: FQ traffic shaper added to Linux
- 2016: BBRv1 (Bottleneck Bandwidth and Round-trip propagation time)
- 2019: BBRv2

See Matt Mathis's talk from March 2020 for excellent summary of TCP congestion control history

https://www.es.net/science-engagement/ci-engineering-lunch-and-learn-series

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On a 10 Gb/s LAN path the impact of low packet loss rates is minimal On a 10 Gb/s WAN path the impact of low packet loss rates is enormous

Beyond your metro area, zero loss is essentially required for performance When global collaboration is the norm, nobody can afford to be a local-only resource

TCP Congestion Control

- Congestion Control Algorithms fall into 2 general categories:
 - Loss-based. (e.g.: Reno and Cubic)
 - Sender slows down if loss is detected
 - Delay-based (e.g.: Vegas and Fast)
 - Sender slows down if additional delay is detected
- The Internet has largely used loss-based congestion control algorithms
 - assumes that packet loss is equivalent to congestion
- But packet loss is not equivalent to congestion.
 - Congestion: network path has more data in flight than the bandwidth-delay product (BDP) of the path.
- Loss-based CC is increasing problematic due to:
 - Shallow buffers: in shallow buffers, packet loss happens before congestion
 - Deep buffers: at bottleneck links with deep buffers, congestion happens before packet loss.
- The BBR congestion control algorithm takes a different approach
 - Does not assume that packet loss = congestion,
 - BBR builds a model of the network path in order to avoid and respond to actual congestion.
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BBRv2 TCP

- Addresses the following BBRv1 issues
 - Low throughput for Reno/CUBIC flows sharing a bottleneck with bulk BBR flows
 - High packet loss rates if bottleneck queue < 1.5*BDP
 - Low throughput for paths with high degrees of aggregation (e.g. wifi)
 - Throughput variation due to low cwnd in PROBE_RTT
 - Adapts bandwidth probing for better coexistence with Reno/CUBIC
- <u>https://datatracker.ietf.org/meeting/104/materials/slides-104-iccrg-an-update-on-bbr-00</u>
- BBRv2 is currently being used on a small percentage of global YouTube traffic, and deployed as default TCP congestion control for internal Google traffic
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https://datatracker.ietf.org/meeting/104/materials/slides-104-iccrg-anupdate-on-bbr-00



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ESnet's BBRv2 Evaluation Project

Evaluate BBRv2 for large science data transfers

- 40G / 100G hosts ("Data Transfer Nodes")
- Data transfer tools that use parallel flows (e.g.: GridFTP)
- Focus is on R&E (research and education) networks, not commodity internet
 - Very different use case than Google/YouTube requirements
- Share results with protocol dev community and gather feedback
- Anticipate future small-buffer, high-BDP networks and wider adoption

Key question: will BBRv2 enable scientific applications to perform well in the absence of deep switch and router buffers?

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See: https://github.com/google/bbr



Host network settings (everything else is Ubuntu 20 system default) net.core.rmem_max = 536870912 net.ipv4.tcp_rmem = 4096 87380 268435456 net.ipv4.tcp_wmem = 4096 65536 268435456 net.core.default_qdisc = fq net.ipv4.tcp_no_metrics_save = 1

'real world' Testing

Source Node:

- 40G host directly connected to ESnet backbone
- Ubuntu 20, 5.10.0 kernel with bbr2 patches
- perfSONAR Testpoint Docker container
 - <u>https://docs.perfsonar.net/install_options.html</u>
 - perfSONAR only allows 1 throughput test to be run at a time

Destination Nodes:

- There are roughly 2000 registered perfSONAR hosts worldwide
 - most of which allow testing from ESnet
 - many of which allow testing from anywhere
 - most restrict testing to 1 minute, but ESnet allows longer tests from other ESnet hosts.
- Tests are running on production networks, with no control over competing traffic
- We selected a variety of test hosts of various RTTs and various loss characteristics



Host network settings (everything else is Ubuntu 20 system default) net.core.rmem_max = 536870912 net.ipv4.tcp_rmem = 4096 87380 268435456 net.ipv4.tcp_wmem = 4096 65536 268435456 net.core.default_qdisc = fq net.ipv4.tcp_no_metrics_save = 1

Test Harness

```
• Python program to facilitate running tests and collecting instrumentation data.
• Sample config file entry:
[pscheduler bbr2 p16]
type = perfSONAR
enabled = true
iterations = 10
src = localhost
dst = 10.201.1.2
src-cmd = pscheduler task --format json throughput --congestion=bbr2 --
ip-version 4 --parallel 16 --duration PT5M --dest {dst}
pre-src-cmd = /usr/sbin/sysctl -w net.ipv4.tcp_congestion_control=bbr2
post-src-cmd = /usr/sbin/sysctl -w net.ipv4.tcp congestion control=cubic
tcpdump = true
tcpdump-filt = -s 128 - i ens2np0 "host {dst} and port 5201"
netem-loss = 0.001
lat-sweep = 2, 5, 10, 20, 30, 50
pacing = 2.4gbit
                                                                  Snet "
```

Raw Data

Our test harness has the ability to collect the following:

- iperf3 JSON output (as reported by pscheduler tool)
- ss (socket stats)
- tcpdump / tcptrace
- mpstat (CPU load)

The data used to generate these plots is available at:

• https://downloads.es.net/INDIS-2021/



Testing / Plotting Methodology and Terminology

- Parallel Flow tests all use 16 flows
 - This is a common default for Globus and other DTN tools
- "non-overlapped" means a 16 flow CUBIC test, followed by a 16 flow BBRv2 test
- "overlapped" means 8 CUBIC flows and 8 BBRv2 flows, all at the same time
- Netem-based results have netem setting in the lower right of the plot





Fig 2 in paper Single flow, non-overlapped, Higher RTT on the right



Figure 3 in paper Parallel flows, Much higher RTT on right



Figure 4 in paper Higher RTT on right



Figure 5 in paper Much higher RTT on right



BBRv2 does much better with smaller buffers CUBIC does slightly better with large buffers



Figure 6 in paper Non-overlapped on left, overlapped on right Flows are paced to 2.4G, but that still significantly over-subscribes the receive host



Figure 8 in paper similar results from the testbed, but not quite as dramatic: 4x vs 20x, possibly due to more buffering



Figure 9 in paper

Paper by Cao et all in the related work section also shows CUBIC 4x faster than BBRv2 with very large buffers on Mininet



Figure 12 in paper 8 flows on the left, 16 on the right For BBRv2, parallel flows help most with RTT > 80ms



Figure 13 in paper



Figure 14 in paper

<text><text><code-block></code>

Tested the params in bold



Figure 15 in paper

Test Variability

- We ran 10 runs of each experiment configuration, and computed the coefficient of variation (CV) of each
 - CV is defined as the ratio of the standard deviation to the mean.
 - The higher the coefficient of variation, the greater the level of dispersion around the mean.
- The CV for all experiments was < 1 (i.e.: reasonable)
- BBRv2 results were 4-5 times more stable than CUBIC based on the CV
- See the paper for more details

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Fairness to CUBIC

- Under some circumstances, BBRv2 is unfair to CUBIC
 - High-BDP paths with packet loss (e.g. from shallow buffer switch or congestion)
 - Speed mismatch (e.g. 100G host to 10G host)
- In theory, it is useful to study fairness, because it helps us understand protocols
- In practice, CUBIC requires very expensive engineering to be competitive with BBRv2
 - Very low packet loss requires deep buffers, significant human effort especially for high-BDP environments (e.g. science/DTN workloads)
 - How should we account for the difference in cost to achieve "fairness?"
- Practical deployment concerns are likely to favor the adoption of BBRv2 and the phase-out of CUBIC over time
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Next Steps

- 100G Testing
 - Are there any surprises at 100G?
- More buffer testing with other small buffered devices
- More BBRv2 parameter sweep testing
 - Especially at 100G



Key Takeaways

- BBR (both v1 and v2) does much better than CUBIC on lossy paths
 - The higher the loss rate and RTT, the more BBR wins out.
- Faster hosts sending parallel flows to slower hosts leads to packet loss
 - BBR does much better than CUBIC in this situation.
- The BBRv1 retransmit rate is unacceptably high with parallel flows, and is very unfair to CUBIC
 - BBRv1 should not be used with parallel data transfer applications.
- BBR prefers smaller switch buffers, and CUBIC prefers larger buffers.
 - As network interface speed increases, larger and larger buffers are impractical (and thus more expensive)
 - Therefore BBR will be a better choice in the future.



Run your own tests

- Install BBR kernel patch: https://github.com/google/bbr/blob/v2alpha/README.md
- Customized Docker container for running your own perfSONAR testpoint on a bbr2 enabled host:
 - https://hub.docker.com/r/dtnaas/perfsonar-testpoint
- Test harness source code:
 - https://github.com/esnet/testing-harness

Our tests used this pscheduler command: pscheduler task --priority 100 --format json throughput --ip-version 4 -parallel 4 --duration PT60S --dest hostname

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For more options, run: pscheduler task throughput --help

For more information

- BBRv2:
 - https://groups.google.com/g/bbr-dev
 - Links to all of Google's BBR papers and talks can be found there.
- Relevant pages on FasterData:
 - https://fasterdata.es.net/science-dmz/DTN/tuning/
 - https://fasterdata.es.net/network-tuning/packet-pacing/
- All data collected for this paper are available at
 - https://downloads.es.net/INDIS-2021/.
 - This includes output from *iperf3* and *ss*, as well at the gnuplot files used to generate the plots in this paper.

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TABLE II: COMPARING MEAN (M) & COEF. OF VARIANCE (C.V) FOR ESNET TESTBED.

		RTT < 30ms RTT						≥ 30ms		
Test		BBRv2		CU	BIC	BB	Rv2	CUBIC		
		Mean	C.V.	Mean	C.V.	Mean	C.V.	Mean	C.V.	
No loss	bbrv2/cubic - p1	9.6533	0.0030	9.8799	0.0024	9.4749	0.0080	9.8435	0.0019	
	bbrv2/cubic - p16	9.7891	0.0064	9.8827	0.0007	9.8044	0.0039	9.8348	0.0029	
	both - p16	3.1188	0.1834	6.7642	0.0849	3.3604	0.0627	6.4739	0.0334	
0.001.0	bbrv2/cubic - p1	9.6545	0.0021	3.3341	0.4694	9.4834	0.0073	1.2988	0.1541	
0.001%	bbrv2/cubic - p16	9.7918	0.0061	9.8819	0.0008	9.7838	0.0041	9.7794	0.0071	
loss	both - p16	4.2258	0.1360	5.6566	0.1026	4.9394	0.0390	4.8894	0.0435	
0.01 % loss	bbrv2/cubic - p1	2.3477	0.0017	1.0500	0.5585	2.3041	0.0018	0.2454	0.0722	
	bbrv2/cubic - p16	9.7586	0.0053	9.0397	0.1325	9.8131	0.0017	3.9534	0.0205	
	both - p16	6.1650	0.1954	3.6777	0.3352	8.0112	0.0068	1.7950	0.0276	
0.1% loss	bbrv2/cubic - p1	8.8108	0.0788	0.3308	0.5180	8.7230	0.0746	0.0472	0.2533	
	bbrv2/cubic - p16	9.7969	0.0037	5.1883	0.5058	9.7824	0.0038	0.7438	0.2552	
	both - p16	7.5959	0.1542	2.2361	0.5284	9.4057	0.0068	0.3652	0.2545	
100G-to-10G	bbrv2/cubic - p16	-	-	-	-	9.6275	0.0004	9.4377	0.0344	
	both - p16	-	-	-	-	9.2094	0.0028	0.4254	0.0473	

		RTT < 30ms			RTT ≥ 30ms						
Test		BBRv2		CUBIC		BBRv2		CUBIC			
			Mean	C.V.	Mean	C.V.	Mean	C.V.	Mean	C.V.	
10C-to-10C	ESNET	both - p16	4.7750	0.0726	5.0057	0.1122	4.7733	0.0055	4.8860	0.0043	
103-10-103	NON-ESNET	both - p16	4.2526	0.0742	4.6333	0.0309	3.9346	0.2188	3.8361	0.2972	
40G-to-10G	DONIDO	both - p8	4.5768	0.2991	5.2852	0.2399	8.3485	0.0899	1.2883	0.6450	
	ESNET	both - p16	4.3490	0.2291	5.1557	0.1906	6.9421	0.1222	2.4023	0.3816	
	NON PENET	both - p8	-	-	-	-	8.2697	0.0626	2.9697	0.2500	
	NON-ESNET	both - p16	-	-	-	-	8.1870	0.1512	1.9163	0.6094	
		-			-			-			EO
											ESUB









